

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a single RS-232/RS-485 interface used for drive configuration and setup. Drive commissioning is accomplished using DriveWare® 7, available for download at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Ran	nge
Peak Current	15 A (10.6 A _{RMS})
Continuous Current	7.5 A (7.5 A _{RMS})
Supply Voltage	100 - 240 VAC



Features

- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ✓ Fully Digital State-of-the-art Design
- Fully Configurable Current, Voltage, Velocity and Position Limits
- PIDF Velocity Loop

- PID + FF Position Loop
- Compact Size, High Power Density
- 16-bit Analog to Digital Hardware
- Built-in brake/shunt regulator
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching

MODES OF OPERATION

- Current
- Position
- Velocity

COMMAND SOURCE

- PWM and Direction
- Encoder Following
- Over the Network±10 V Analog
- 24V Step and Direction
- Sequencing
- Indexing
- Jogging

FEEDBACK SUPPORTED

- Resolver
- ±10 VDC Position
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

INPUTS/OUTPUTS

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

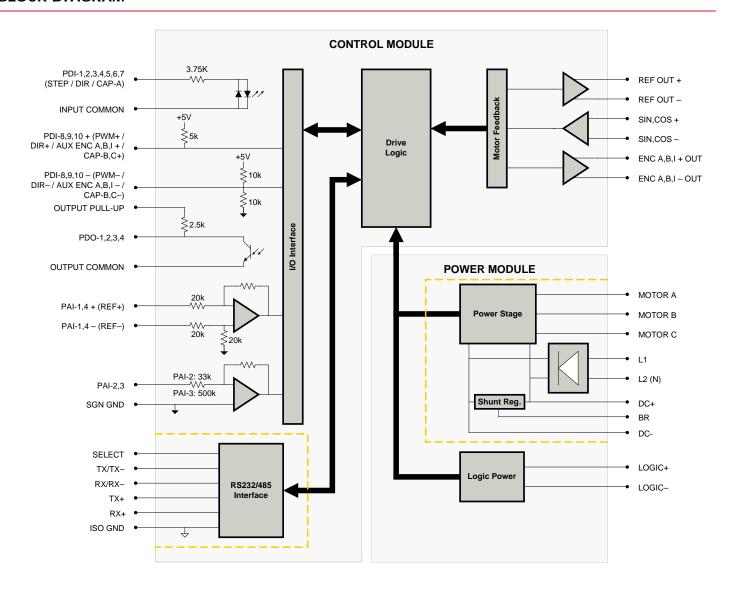
COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS





BLOCK DIAGRAM



	Information on Approvals and Compliances		
US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.			
(€	Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.		
COMPLIANCE	RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.		





SPECIFICATIONS

Power Specifications Description Units Value			
Rated Voltage	VAC (VDC)	240 (339)	
AC Supply Voltage Range	VAC	100 - 240	
AC Supply Minimum	VAC	90	
AC Supply Maximum	VAC	264	
AC Input Phases	-	1	
AC Supply Frequency	Hz	50 - 60	
DC Supply Voltage Range ¹	VDC	127 - 373	
DC Bus Over Voltage Limit	VDC	394	
DC Bus Under Voltage Limit DC Bus Under Voltage Limit	VDC	55	
	-		
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)	
Maximum Peak Output Current ²	A (Arms)	15 (10.6)	
Maximum Continuous Output Current ³	A (Arms)	7.5 (7.5)	
Max. Continuous Output Power @ Rated Voltage4	W	2415	
Max. Continuous Power Dissipation @ Rated Voltage	W	127	
Internal Bus Capacitance	μF	540	
External Shunt Resistance Minimum Resistance ⁵	Ω	25	
Minimum Load Inductance (Line-To-Line) ⁶	μH	600	
Switching Frequency	kHz	20	
Maximum Output PWM Duty Cycle	%	100	
Low Voltage Supply Outputs	-	+5 VDC (250 mA)	
		Specifications	
Description	Units	Value	
Communication Interfaces	-	RS-485/232	
Command Sources	-	±10 V Analog, 24V Step and Direction, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging	
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Resolver, Tachometer (±10 VDC)	
Commutation Methods	-	Sinusoidal	
Modes of Operation	-	Current, Position, Velocity	
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)	
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Shot Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4	
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/0	
Primary I/O Logic Level	-	24 VDC	
Current Loop Sample Time	μs	50	
Velocity Loop Sample Time	μs	100	
Position Loop Sample Time	μs	100	
Resolver Reference/Excitation Signal	Vrms	4 Vrms @ 5 kHz	
Expected Resolver Transformation Ratio	Vrms	0.5	
Feedback Resolution / Emulated Encoder Resolution ⁷	bit	High Res: 14 (16384 counts/resolver cycle), Low Res: 12 (4096 counts/resolver cycle)	
Maximum Motor Speed Per Feedback Resolution	RPM	High Res: 5000, Low Res: 20000	
Internal Shunt Regulator		Yes	
Internal Shunt Resistor	-	No	
mornal origin (Costolor	Mechanic	al Specifications	
Description	Units	Value	
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
Size (H x W x D)	mm (in)	177.495 x 123.393 x 44.450 (6.988 x 4.858 x 1.750)	
Weight	g (oz)	894 (31.5)	
Heatsink (Base) Temperature Range ⁸	°C (°F)	0 - 75 (32 - 167)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Form Factor	-	Panel Mount	
Cooling System	-	Natural Convection	
IP Rating		IP10	
+24V LOGIC Connector		2-port, 5.08 mm spaced, enclosed, friction lock header	
AUX ENCODER Connector		15-pin, high-density, male D-sub	
		9-pin, female D-sub	
COMM Connector FEEDBACK Connector	-		
	<u> </u>	15-pin, high-density, female D-sub	
I/O Connector	-	26-pin, high-density, female D-sub	
POWER Connector	-	10-port, 5.08 mm spaced, enclosed, friction lock header	

Notes

- Large inrush current may occur upon initial DC supply connection to DC Bus.
 Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
- Continuous A_{rms} value attainable when RMS Charge-Based Limiting is used.
- P = (DC Rated Voltage) * (Cont. RMS Current) * 0.95.

 ADVANCED Motion Controls recommends using an external fuse in series with the shunt resistor. A 3 amp motor delay fuse is typical. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Higher and lower resolution options are available. Contact Applications Engineering for more information.
- Additional cooling and/or heatsink may be required to achieve rated performance.

ELECTROMATE Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com



PIN FUNCTIONS

	+24V LOGIC - Logic Power Connector			
Pin	Pin Name Description / Notes I/O			
1	1 LOGIC GND Logic Supply Ground GNE		GND	
2	LOGIC PWR	Logic Supply Input	İ	

AUX ENCODER - Auxiliary Feedback Connector			
Pin	Name	Description / Notes	1/0
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Single-Ended Signals Leave Negative Terminal Open)	I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	(For Single-Ended Signals Leave Negative Terminal Open)	I
8	PDI-10 +	Programmable Digital Input (For Single-Ended Signals Leave Negative Terminal Open)	
9	PDI-10 -	Programmable Digital input (For Single-Ended Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-4 +	Differential Programmable Analog Input (12-bit Resolution)	
15	PAI-4 -		

	COMM - RS232/RS485 Communication Connector		
Pin	Name	Description / Notes	1/0
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	Į.
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	0
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I I
4	RESERVED	Reserved	-
5	ISO GND	Isolated Signal Ground	IGND
6	RS485 TX+	Transmit Line (RS-485)	0
7	RESERVED	Reserved	-
8	RS485 RX+	Receive Line (RS-485)	l l
9	RESERVED	Reserved	-

	FEEDBACK - Feedback Connector		
Pin	Name	Description / Notes	1/0
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	REF OUT +	Bosolver Reference/Evoltation Output	0
5	REF OUT -	Resolver Reference/Excitation Output	0
6	SIN+	Deschar Cine least	I
7	SIN-	Resolver Sine Input	1
8	COS+	Decelver Cooling Input	l l
9	COS-	Resolver Cosine Input	1
10	RESERVED	Reserved	-
11	RESERVED	Reserved	-
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-3	Programmable Analog Input (12-bit Resolution)	1
15	RESERVED	Reserved	-





		I/O - Signal Connector	
Pin	Name	Description / Notes	1/0
1	PDO-1	Isolated Programmable Digital Output	0
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	0
4	PAI-1 + (REF+)	Differential Droggommobile Analog Input or Deference Cignal Input (46 hit Decelution)	I
5	PAI-1 - (REF-)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	1
7	SGN GND	Signal Ground	SGND
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	1
10	PDO-3	Isolated Programmable Digital Output	0
11	PDI-1	Isolated Programmable Digital Input	
12	PDI-2	Isolated Programmable Digital Input	
13	PDI-3	Isolated Programmable Digital Input	
14	PDO-4	Isolated Programmable Digital Output	
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	
16	SGN GND	Signal Ground	SGND
17	PDI-4 (STEP)	Isolated Programmable Digital Input or Step	I
18	PDI-6 (DIR)	Isolated Programmable Digital Input or Direction	I
19	PDI-7 (CAP-A)	Isolated Programmable Digital Input or High Speed Capture	1
20	ENC A+ OUT	Facility of Face des Changel A Outset	0
21	ENC A- OUT	Emulated Encoder Channel A Output	0
22	ENC B+ OUT	Emulated Encoder Channel P. Output	0
23	ENC B- OUT	Emulated Encoder Channel B Output	
24	ENC I+ OUT	Familiated Familia Indian Outside	0
25	ENC I- OUT	Emulated Encoder Index Output	0
26	SGN GND	Signal Ground SG	

	POWER - Power Connector		
Pin	Name	Description / Notes	1/0
1	MOTOR A	Motor Phase A	0
2	MOTOR B	Motor Phase B	0
3	MOTOR C	Motor Phase C	
4	SHIELD	Motor cable shield. Internally connected to protective earth ground.	
5	PE	Protective Earth Ground	
6	L1	AC Complete and (Cingle Diseas)	
7	L2 (N)	AC Supply Input (Single Phase)	1
8	DC+	Internal DC Bus Voltage	
9	BR	External Brake Resistor Connection. If using an external brake resistor, connect between this port and DC+.	-
10	DC-	Internal DC Bus Voltage	I/O





HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
Switch	Description	On	Off
1	Bit 0 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0

Additional Details

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

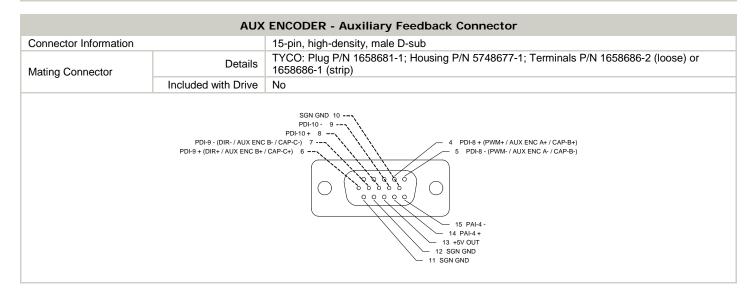
Baud Rate (kbps)	Value For Bit Rate Setting
Load from non-volatile memory	0
9.6	1
38.4	2
115.2	3





MECHANICAL INFORMATION

+24V LOGIC - Logic Power Connector		
Connector Information 2-port, 5.08 mm spaced, enclosed, friction lock header		
Mating Connector Details Included with Drive		Phoenix Contact: P/N 1757019
		Yes
2 LOGIC + 1 LOGIC -		

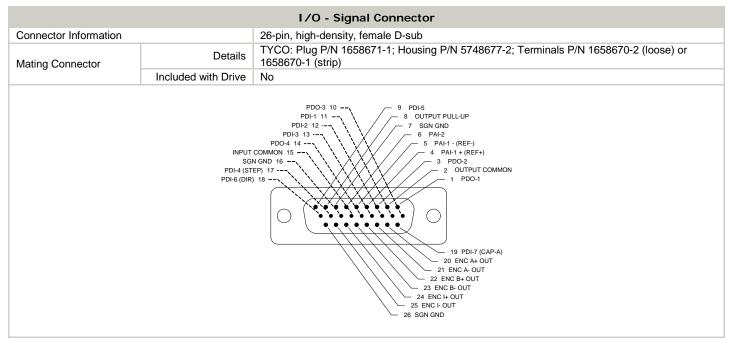


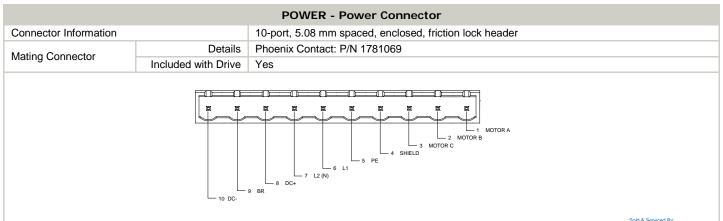
COMM - RS232/RS485 Communication Connector			
Connector Information		9-pin, female D-sub	
Mating Connector	Details	TYCO: Plug P/N 205204-4; Housing P/N 5748677-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)	
	Included with Drive	No	
5 ISO GND 3 RS232 RX / RS485 RX- 2 RS232 TX / RS485 TX- 1 SELECT 6 RS485 TX+ 8 RS485 RX+			





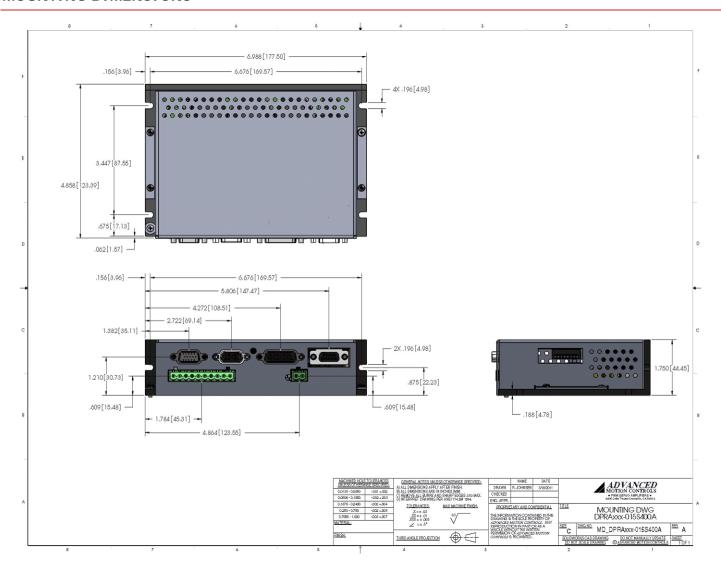
FEEDBACK - Feedback Connector			
Connector Information		15-pin, high-density, female D-sub	
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)	
	Included with Drive	No	
SIN+ 6 5 REF OUT - SIN- 7 4 REF OUT + COS+ 8 COS- 9 12 SGN GND 13 +5V OUT 14 PAI-3			







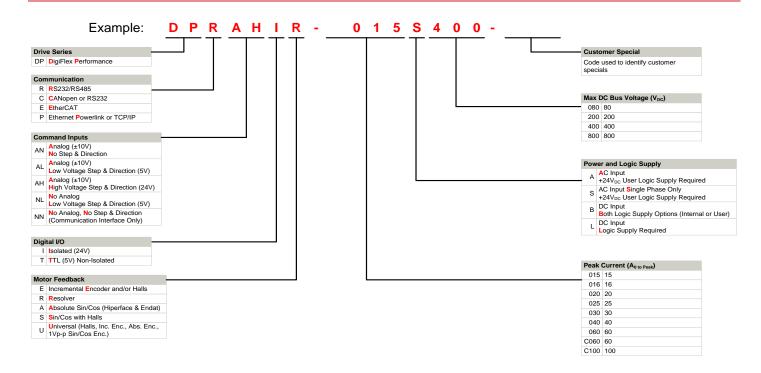
MOUNTING DIMENSIONS







PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- No Outer Case
- ▲ Increased Current Resolution
- Increased Temperature Range
- Integrated System I/O

- ▲ Tailored Project File
- Silkscreen Branding
- Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.





All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.